AN ICEBERG DRIFT MODEL FOR THE BARENTS SEA

LOM August 2007

Intissar Keghouche



Outline

- Circulation in the Barents Sea
- Sources of icebergs
- Iceberg model equation
- Validation against data from Russian buoy deployment in 1989
- Conclusion & future work

Circulation



Sources of icebergs



Average 300 000 tons (90 x 60 x 15m) (Ice Data Acquisition Project, IDAP, 1994) Max. observed 6.2 mill. tons (320 x 270 x 40m) (IDAP) Average speed 0.5 knots, maximum 2 knots. Mostly follow southerly current 40E (IDAP)

Iceberg drift model equation (Lichey 2001)

$$M*\frac{d\vec{u}}{dt}=\vec{F}_A+\vec{F}_W+\vec{F}_C+\vec{F}_{SS}+\vec{F}_{SI}$$

M: Mass

F_A: Atmospheric drag

F_w: Ocean drag

F_c: Coriolis force

F_{ss}: Force due to the sea surface slope

F_{si}: Force due to sea ice

Iceberg drift model Ocean(W) and Air(A) drag components

Smith and Banke, 1983 relationship:

$$\vec{F}_x = (\frac{1}{2} * \rho_x * c_x * A_{vx} + \rho_x * c_{dx} * A_{hx}) * |\vec{v}_x - \vec{u}| * (\vec{v}_x - \vec{u})$$

- _X: refers to air(A) and water(W)
- ρ_x : medium density
- C_x : dimensionless coeff of resistance
- C_{dx}: dimensionless drag coeff for very smooth surface
- A_{vx} : area of iceberg wall in contact with the wind /oceanic flow
- A_{hx}: horizontal area of iceberg in contact with the wind (top)/ocean (base) current
- V_x : wind/ocean current velocity
- u: iceberg velocity

Iceberg drift model Coriolis and Sea surface slope components

$$ec{F_C} = 2 * M * \Omega * \sin \phi * ec{k} imes ec{u}_{
m c}$$

 $\vec{F}_{SS} = -M\vec{g} * \sin lpha$

- Ω : rotation of the Earth
- k: unit vector perpendicular to the Earth
- g: acceleration due to the gravity
- α : tilt of the sea surface estimated from the barotropic part of the modeled ocean velocity

Iceberg drift model Sea Ice Forces

$$\vec{F}_{SI} = \begin{cases} 0 : A \le 15\% \\ \frac{1}{2} * \rho_{SI} * c_{SI} * A_{SI} |\vec{v}_{SI} - \vec{u}| (\vec{v}_{SI} - \vec{u}) : 15\% < A < 90\% \\ -(\vec{F}_A + \vec{F}_W + \vec{F}_C + \vec{F}_{SS}) : A \ge 90\% \text{ and } P \ge P_s \end{cases}$$
$$P = P^* * h * \exp\{-20(1 - A)\}$$

A: sea ice concentration

 ρ_{si} : sea ice density

 C_{si} : sea ice coefficient of resistance

Asi: product of sea ice thickness and iceberg width

 V_{si} : sea ice velocity

P: sea ice strength parameter (resistance of sea ice)

P_s and P^{*}: threshold value and empirical coefficient *h*: ice thickness

Forcing computation

Daily averages forcing

- 10m wind field from ERA40 with
 1.125⊕resolution
- Sea Ice data from a nested configuration of HYCOM. TOPAZ gives boundary conditions to a Barents Sea model of 9-12 km resolution
- Ocean velocities interpolated over the iceberg draft from HYCOM Barents Sea model of 9-12 km resolution
- Tides are not included



Data: iceberg #1792 (IDAPreport89) Drifted from August 8 to November 27th 1989



3 exp with 3 ≠ iceberg drafts 8m



3 exp with 3 ≠ iceberg drafts 13m



3 exp with 3 ≠ iceberg drafts 18m



Drift speed



N=111

N=8854

Icebergs velocities distributions



N=111

Sea ice strength characteristics ex: 8m draft iceberg

 $P = P^* * h * \exp\{-20(1-A)\}$



Forcing velocities ex: 8m draft iceberg



Conclusion

- Modeled trajectories and velocity distributions are comparable with the observed one
- The model is sensitive to the iceberg draft size
- The wind is the dominant contribution in this example

Future work

Test the model on other iceberg drift events

Model improvements

- Include tides
- Melting
- Higher resolution of the forcing fields (STORM winds)

Ensemble run with perturbation of

- the size of the icebergs
- the initial position of the iceberg
- each forcing component

Thank you !

